The goal of modern neurosurgery is to improve the survival rates and quality of life of patients with surgically treatable intracranial lesions. It is known, however, that tumor progression and survival in cases of malignant intracranial tumors is contingent on the extent of tumor removal. The protection of functions potentially at risk during surgery is facilitated by functional mapping of critical eloquent areas. The gold standards for mapping eloquent areas of the brain are invasive cortical stimulation and somatosensory evoked potential monitoring.

A number of secondary physiological changes occur as a result of neuronal activity in the brain. Measurable changes such as glucose utilization led to the development of functional mapping with 18FDG-PET. It was also found that another of these changes, local differences in oxygen use, could be demonstrated and localized using MR imaging, which led to the development of BOLD fMR imaging. The introduction of frameless intraoperative neuronavigation systems such as StealthStation (Medtronic, Boulder, CO) or Vector Vision (BrainLab AG, Heimstetten, Germany) has allowed the precise coregistration and transfer of fMR imaging data into the surgical field. Understandably, however, the acceptance of MR imaging by neurosurgeons; the stakes are obviously different. Although the status of fMR imaging currently is investigational; it is an evolving technology that shows both future promise and present-day utility. In some instances, it has been used successfully in lieu of invasive mapping tools. Indeed, in certain cases, evidence exists that fMR imaging mapping may be more appropriate than cortical stimulation. Its shortcomings can be categorized into the following two broad categories: 1) technical, which will be at the very least partially overcome by ongoing technical advancement; and 2) neuroscientific understanding in general, which otherwise applies to all modalities of brain mapping (including direct cortical stimulation and somatosensory evoked potential monitoring). When not used as an outright substitute for invasive mapping, fMR imaging has a well-documented adjunctive role in optimizing surgical procedures and outcomes that belie its investigational status.

The technical background of fMR imaging

The feasibility of using MR imaging for mapping of neuronal activation with the BOLD technique was first demonstrated in the human brain in 1992 by Kwong, et al., and Ogawa, et al., who used a simple visual perception task, and by Bandettini, et al., who used a motor task. Since then, several investigators have described the use of fMR imaging for presurgical mapping, many of whom correlated their findings with invasive cortical mapping data.

Like other functional neuroimaging modalities such as PET, BOLD fMR imaging is based on secondary physio-
logical responses to brain activation. Neuronal activity initially causes a transient increase in oxygen extraction, which is quickly followed by compensatory vasodilation and resultant net overall increase in blood oxygen content as bound oxyhemoglobin. Because the relative amount of deoxygenated blood (that is, deoxyhemoglobin) is lowered, a slight increase in signal intensity occurs because of the corresponding relative decrease in the spin-dephasing paramagnetic effects of deoxyhemoglobin. Although this coupling of blood oxygen changes and neuronal activation is tight and well localized, the response time is relatively slow, measured in seconds, relative to the time of neuronal activation, which is measured in tens or hundreds of milliseconds. Thus, functional tasks are designed to be repetitive (for example, finger–thumb tapping) and to take place typically over the course of 20 to 40 seconds, then cycled with “rest” periods of equal length for several cycles to increase the signal-to-noise ratio and the statistically accuracy of observed “activations.”

Magnetic resonance imaging sequences used to create BOLD fMR imaging have evolved in line with the progression of MR imaging technology. Earlier studies were performed using standard gradient-echo 1.5-tesla acquisitions, acquired in single-section mode that involved conventional 10-mT/m gradients. The application of echo-planar imaging gradients has resulted in significant decrease in image acquisition times. Multisection-mode acquisitions with echo-planar spin echo or single-shot gradient-recalled echo-planar imaging in which high-performance gradients are used now allow even faster acquisitions. High-field 3-tesla imaging further enhances spatial resolution and signal-to-noise effects.

**Task Design**

Although the task is cycled between periods of activity and rest, there is no standardization of length or number of cycles. Task cycles can vary considerably, typically from 12 to 30 seconds, but must be long enough to allow the occurrence of hemodynamic changes at the cellular and macrocellular levels, while imaging data are acquired from 2.5 to 5 minutes. The data are then analyzed pixel by pixel, corrected for linear baseline drift of the MR imaging signal, and maps of cortical activity are created using statistical methods in which a correlation coefficient threshold is selected to produce a probability of a false-positive activation due to random noise (p < 0.0001 to p < 0.05 typically) (Fig. 1). Many task variants have been developed, typically to include localization of the sensory and motor cortices, Broca and Wernicke speech areas, and primary and secondary visual areas. Motor tasks have been accomplished by simple finger–thumb tapping and in other cases by multiple finger–thumb tapping, self-paced clenching and spreading of the hand, or sponge squeezing. Tactile stimulation has included palm brushing, administration of air puffs to the hand, and scratching the surface of the hand. Language tasks have included picture naming by internal (silent) or vocalized speech, generating verbs, generating words in alphabetical order, listening to recordings of spoken words, or designating a category in response to an auditory presentation of nouns. Visual tasks have included intermittent photic stimulation with MR imaging–compatible binoculars and various projected pattern stimuli. Viable future directions would conceivably include task designs for memory functions, high-level cognitive tasks, and perhaps even emotion and affect.

**CURRENT CONSIDERATIONS**

**Technical Limitations**

**Venous Effects.** A limitation of positive BOLD fMR imaging is that the signal is not confined to the microvasculature but spreads into veins that drain blood from the activated brain tissue, and these draining veins may be several millimeters or up to a centimeter away from the actual site of neuronal activation. Thus, the degree to which blood flow changes correlate spatially with neuronal activity is not known. Because local hemodynamic effects are the basis for BOLD fMR imaging, false-positive activity within adjacent draining veins can complicate interpretation.

**Patient Motion and Compliance.** The primary reason for the failure of fMR imaging examinations is patient-generated motion. As examination times have decreased with faster imaging modalities, such as single-shot echo-
sensitivity of the tool. Hirsch, et al., 17 postulated that overall sensitivity would be improved by targeting common critical areas with multiple tasks, including functions repeated in both “active” (volitional) and “passive” (receptive) modes. This method was predicated on the existence of redundancy in functional areas of cortical activation for related tasks. It is known, for example, that functional overlap exists between the pre- and postcentral gyri for both motor function (active tapping) and sensory stimuli (passive touching). For language-related function, when the only task used was silent picture naming, the Wernicke area on the superior temporal gyrus was identified in only 73%. When the task involved listening to spoken words, however, activation of this area was 100%. Visual tasks designed to exploit this overlapping effect included viewing of a reversing checkerboard stimulus (passive) and viewing of pictures during a naming task that requires a response (active). Overall, administering the battery of multiple tasks in healthy volunteers, Hirsch reported 100% sensitivity for identifying the language-related cortex in the superior temporal gyrus, 100% for identifying the central sulcus and visual cortex, and 93% in identifying the Broca area.17 Compared with the results of Wada testing for identification of hemispheric language dominance, there was 100% correlation.1,17

What of patients with brain tumors, who, along with those suffering from epilepsy, would be the target population for these procedures? Normal brain anatomy is frequently distorted by tumor mass effect and edema (Fig. 2). In 125 surgically treated patients with disease in the region of the central sulcus, Hirsch, et al.,17 reported that the active area of the postcentral gyrus was identified in 94% when a tactile stimulation task was undertaken and in the precentral gyrus identified in 89% when the finger–thumb tapping paradigm was performed; overall localization of the central sulcus was possible in 97% of patients. For language functions in surgically treated patients with tumors in the specific regions, the Wernicke area was identified in 31 (91%) of 34 patients and the Broca area in 17 (77%) of 22 patients. Visual cortex (calcarine sulcus and inferior occipital gyrus) was identified in six of six patients with lesions in these areas. In their series, the most common cause of failure was neurological deficits such as cognitive loss or tumor-related expressive or receptive aphasia. The second-most common cause was excessive (not correctable) head motion. Marginal compliance was also cited, and false-negative results were extremely low.

Localization Accuracy and Direct Electrophysiological Testing

The spatial accuracy of fMR imaging is within 5 mm, which is well within the approximately 10-mm spread of electrical current to adjacent cortex known to occur when using invasive mapping modalities. Numerous investigators have corroborated the spatial specificity of fMR imaging vis-à-vis electrocortical mapping and SSEP testing for identifying simple task centers of motor and sensory function, typically within 1 cm.1,10,11,17,19,27,32,34,43,46 Functional MR imaging also has the advantage of being able to identify activation areas deep within the sulci that are not detectable by cortical stimulation at the brain surface.1 Agreement between fMR imaging and electrophysiological testing data, however, appears less clearcut when
it involves complex tasks such as language. The majority of investigators have shown good correlation, particularly if a battery of language tests with functional redundancy (for example, both passive and active tasks that overlap functional areas) was built into the task design. Schlosser, et al., noted excellent spatial localization of language area when using fMR imaging, but spatial extent of language localization was less satisfying. They noted, however, that a single auditory task was used in their fMR imaging study, whereas several tasks were used intraoperatively. Additionally, because the spatial extent of fMR imaging activation is partly related to the statistical threshold at which activations are plotted, lower threshold values would yield a greater number of false-positive values and enlarge the activation area. On the other hand, Roux, et al., reported relatively poor correlation between fMR imaging and direct cortical stimulation data when the complex task of language function was tested, as well as relatively poor reproducibility of results when studies were repeated postoperatively. Their results may also have been affected by the use of limited task redundancy (for example, the study design did not include passive listening in addition to verb generation and naming). Sobottka, et al., reported similar results when comparing 18FDG-PET scanning and intraoperative language testing data. In both cases, it should be noted that electrical current levels necessary to achieve language disruption in cortical stimulation testing are typically not uniform and could stimulate more distant cortex through current spread, particularly if language function lies deeper in a sulcus. What is also not clear is whether the paradigm of direct cortical testing best identifies the locus needing protection for preservation of function. Functional MR imaging delineates more areas of activation related to language and other complex functions than cortical stimulation testing, but the presumably daunting task remains of elucidating the ultimate impact of surgical disruption compared with sparing of each of these areas.

Other limitations of intraoperative testing include only unilateral testing capability, the need for a relatively larger operative exposure, high cost, lengthy intraoperative time, and significant stress on the patient. Alternatively, a two-stage procedure may be used in which a subdural grid is implanted in the first stage to allow functional electrophysiological testing to be performed postoperatively; in the second stage, resection surgery is conducted using a mapping grid generated between stages. This latter approach addresses the sometimes strong psychological burden of direct intraoperative testing for the awake patient in whom a local anesthetic agent has been used. Preoperative fMR imaging assessment can significantly reduce operative time by assisting in the design of craniotomy and surgical approach while minimizing possible brain shifts. In one series, operative time was reportedly reduced by 50%.

The correlation between the repetitive task paradigms used in fMR imaging and the “single-episode” task interruption process used in direct cortical stimulation mapping is not known. It cannot necessarily be assumed, for instance, that repetitive finger-thumb tapping is equivalent to electrode stimulation of the motor homunculus, although presumably some correlation exists. What is also not conclusive is whether the intraoperative cortical stimulation paradigm for any given function necessarily reflects a better delineation of function localization than fMR imaging or other physiological mapping methods. The area of task interruption that occurs with cortical stimulation is a very small zone of less than 10 mm and only includes areas on the surface of the brain, whereas fMR imaging reveals activities in deeper areas. It could be argued that fMR imaging, because it provides a more anatomically global view of cerebral function, would more
Functional MR imaging for brain mapping

accurately depict both primary and secondary (and lower-order) sites of function. Particularly for more complex tasks that may activate multiple and bilateral areas, fMR imaging may in some cases be a more appropriate guide for conservative resection than cortical stimulation. Work to date involving higher-field magnets (3-tesla) has conclusively shown a significant increase in spatial resolution and signal-to-noise ratio. This allows the use of higher statistical thresholds for counting true functional activations without increasing false-positive (noise) activations, which could in part address some of the aforementioned discrepancies with cortical stimulation.

Clinical Application and Utility

Although a role for fMR imaging as a substitute for invasive brain mapping remains uncertain, its clinical utility transcends its current investigational status. Surgical planning can be significantly enhanced by the incorporation of fMR imaging. Invasive mapping is typically performed if a proposed resection is believed preoperatively to place an eloquent area such as the motor cortex at risk. Because fMR imaging can demonstrate the proximity of eloquent areas to the proposed resection site, it can be used to identify cases in which intraoperative functional mapping will be needed. In some cases, the considerable stress, expense, and operative time added to a resection procedure can be foregone because of the preoperatively acquired fMR imaging data. In fact, Lee, et al., concluded in a review of their experience during a 4.5-year period that the overwhelming emphasis placed on the potential for fMR imaging to replace completely invasive mapping may be misguided because its clinical value was evident without replacing invasive mapping techniques. Overall, fMR imaging studies significantly contributed to determining the feasibility of planned resection, significantly affected surgical planning preoperatively, or selected patients for invasive functional mapping (and aided in guiding intraoperative mapping) in 89% of surgically treated patients with tumors and 91% of those with epilepsy. Of course, beyond these current beneficial effects, work to increase the clinical utility of fMR imaging independent of other methodologies is ongoing.

Coregistration with Neuronavigation Systems

Data from any of the functional imaging modalities (fMR imaging, PET, or magnetoencephalography) can be transferred to neuronavigation systems to provide direct intraoperative guidance; this is accomplished by coregistering the data with the anatomical image, either a 3D computerized tomography or MR image (Fig. 3). Wilkinson, et al., concluded that the additional information provided by fMR imaging, particularly when incorporated into a neuronavigation-guided craniotomy, was highly valuable and enabled safe resection of tumor in locations previously deemed to be too high risk when using a conventional technique without intraoperative cortical mapping. None of their patients suffered permanent neurological deficit after radical tumor debulking.

For certain tumors such as low-grade gliomas with no appreciably defined margins, the radicality of resection margins also needs to be objectively determined intraoperatively. Magnetic resonance imaging is generally unable to distinguish tumor from edema. In these cases, multimodality imaging can be performed by incorporating coregistered tumor images into that of the neuronavigation system along with functional mapping data. Various agents have been used for tumor mapping, including FDG-PET, or 11C methionine, or 20.1 Tl single-photon emission computerized tomography. Sabbah, et al., used a multimodal approach by coregistered integration of Tl SPECT tumor imaging with MR and fMR imaging mapping to optimize tumor resection.

CONCLUSIONS

Identification of eloquent areas of the brain to avoid resection-induced damage is of utmost importance for postoperative quality of life. Although the current standard for identifying these areas continues to be invasive electrophysiological testing, the development of viable noninvasive alternatives would be welcome. Invasive methods necessitate the performance of surgery in the awake patient, which can be a great strain for the patient and the surgeons in a procedure that takes several hours, and even carries the added risk of producing epileptic seizure.

Functional MR imaging has shown significant utility as an adjunctive mapping procedure and, in some cases, as a more appropriate modality for surgical guidance. It is to become an accepted effective alternative to invasive mapping methods, however, further work must be conducted. Issues that warrant further study include the effect of tumor angiogenesis, as mentioned previously; the effects of incidental pathological findings such as atherosclerotic disease; and inter- and intraindividual variations in cerebrovascular anatomy, autoregulation, and cardiac output. Complex tasks such as language and memory present a great challenge for defining suitable testing paradigms. Nonstandard protocols and task designs as well as numerous variations in functional imaging technique represent additional confounding factors requiring study. A multimodal approach is perhaps most likely to become an effective alternative to invasive mapping. Spatial localiza-
tion issues will likely follow the routine use of high-field (3-tesla) fMRI imaging.

The aforementioned standard approaches to functional mapping do not provide information about subcortical white matter. Diffusion-tensor and diffusion-weighted imaging map the directionality of water molecules at the cellular level, thus indicating the orientation of fiber tracts (Fig. 4). In one recent investigation, preoperative cellular level, thus indicating the orientation of fiber tracts (Fig. 4). In one recent investigation, preoperative diffusion-tensor and diffusion-weighted imaging were fused with volume-rendered standard T1-weighted brain image. The aforementioned standard approaches to functional mapping do not provide information about subcortical white matter. Diffusion-tensor and diffusion-weighted imaging map the directionality of water molecules at the cellular level, thus indicating the orientation of fiber tracts (Fig. 4). In one recent investigation, preoperative assessment of white matter tracts was found to be beneficial in surgical planning, allowing identification of tracts that were shifted away from the expected location and allowing for adaptation of the surgical approach to avoid destruction of these tracts.44

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Functional MR imaging for brain mapping


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