Image-guided endoscopic surgery for spontaneous supratentorial intracerebral hematoma

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OBJECTIVE Endoscopic removal of intracerebral hematomas is becoming increasingly common, but there is no standard technique. The authors explored the use of a simple image-guided endoscopic method for removal of spontaneous supratentorial hematomas.

METHODS Virtual reality technology based on a hospital picture archiving and communications systems (PACS) was used in 3D hematoma visualization and surgical planning. Augmented reality based on an Android smartphone app, Sina neurosurgical assist, allowed a projection of the hematoma to be seen on the patient’s scalp to facilitate selection of the best trajectory to the center of the hematoma. A obturator and transparent sheath were used to establish a working channel, and an endoscope and a metal suction apparatus were used to remove the hematoma.

RESULTS A total of 25 patients were included in the study, including 18 with putamen hemorrhages and 7 with lobar cerebral hemorrhages. Virtual reality combined with augmented reality helped in achieving the desired position with the obturator and sheath. The median time from the initial surgical incision to completion of closure was 50 minutes (range 40–70 minutes). The actual endoscopic operating time was 30 (range 15–50) minutes. The median blood loss was 80 (range 40–150) ml. No patient experienced postoperative rebleeding. The average hematoma evacuation rate was 97%. The mean (± SD) preoperative Glasgow Coma Scale (GCS) score was 6.7 ± 3.2; 1 week after hematoma evacuation the mean GCS score had improved to 11.9 ± 3.1 (p < 0.01).

CONCLUSIONS Virtual reality using hospital PACS and augmented reality with a smartphone app helped precisely localize hematomas and plan the appropriate endoscopic approach. A transparent sheath helped establish a surgical channel, and an endoscope enabled observation of the hematoma’s location to achieve satisfactory hematoma removal.

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KEY WORDS endoscopy; hematoma; evacuation; diagnostic and operative techniques

Patients with spontaneous supratentorial intracerebral hemorrhage, especially basal ganglia hemorrhage, who require surgery generally have a poor prognosis. Although no apparent benefit from surgery has been reported for these patients, most patients with this condition actually do undergo surgery. There is currently no single standard surgical treatment, but it has been reported that, in clinical practice, endoscopic hematoma removal has gradually become accepted. Various surgical methods and tools have been adopted, with differing results. We report here a simple, fast, and economical positioning and surgical procedure for endoscopic evacuation of intracerebral hematomas. The method is based on virtual reality using a hospital’s picture archiving and communication system (PACS) and augmented reality using the a smartphone and the Sina neurosurgical assist Android smartphone app, which assists surgeons in precisely placing the obturator and introducing the sheath to the desired target.

Methods

Patient Population

Twenty-five patients with a mean (± SD) age of 65.4 ± 11.1 years were included in the study. Of the 25 patients, 18 had experienced a putamen hemorrhage and 7 had had a lobar cerebral hemorrhage. Hematoma volume and residual hematoma volume were calculated with open-access Slicer software. The hematoma evacuation rate, rate of rebleeding, preoperative and 1-week postoperative Glasgow Coma Scale (GCS) score were recorded.
Scale (GCS) scores, operative time, endoscopic evacuation time, and blood loss were recorded and analyzed. The study was approved by the PLA General Hospital ethics committee, and informed consent was obtained from all patients’ family members.

Inclusion and Exclusion Criteria

Patients with supratentorial spontaneous intracerebral hemorrhage requiring surgery were eligible for inclusion in this study. Patients with hematoma-induced brainstem herniation were not eligible for the study, because decompressive craniectomy and hematoma evacuation is known to produce superior results. Patients were also excluded if they had a hemorrhage in the brainstem and/or cerebellum, bleeding related to vascular malformation, blood clotting disorders, and/or other contraindications to surgery.

Virtual Reality Image Acquisition

After admission to the emergency room, all patients underwent CT to confirm the presence of a cerebral hemorrhage requiring evacuation. Based on the hospital PACS (Philips Healthcare Informatics, Inc.), the hematoma and an outline of the patient’s head were reconstructed. Then, an optimal trajectory was identified.

Augmented Reality Image Development

A reconstructed virtual reality image of the hematoma and the patient’s head was imported into the “Sina neurosurgical assist” Android smartphone app (English version downloadable at no cost from the Google Play Store). The virtual reality and augmented reality images were overlapped using surface markers on the patient’s head and the smartphone camera. Details of this procedure have been reported in the literature. The optimal trajectory determined in the previous step was then designed on the patient’s real head.

Puncture Trajectory Design

For putamen hemorrhages, we adopted a transfrontal trajectory parallel to the sagittal plane. Using axial CT, we measured the distance between the center of the hematoma and the midline. The entrance point was just behind the frontal hairline and parallel to the midline; the target was the center of the hematoma. The distance and the angle from the puncture site to the center of hematoma were calculated.

For patients with lobar cerebral hemorrhages, based on the location, an individualized, shorter pathway was chosen that was far away from all the brain’s eloquent areas.

Endoscopic Hematoma Evacuation Procedure

We used our patented obturator and transparent sheath set (patent number 201210066281.1, Victor Medical Instruments Co.) to create the working channel. After the obturator was precisely positioned in the center of the hematoma, the inner needle was removed and suction was applied to the hematoma with the syringe to reduce intracranial pressure, and then the transparent sheath was introduced to the ideal depth. Through the transparent sheath, the endoscope (diameter 37 mm; 0°; length 18 cm; Karl Storz) and a metal suction device (diameter 3 mm; length 26 cm; Shanghai Sanyou Medical Instrument Co.) as used to suction the bleeding site, and then a unipolar electric knife was placed against the metal aspirator tube for coagulation.

Imaging Follow-Up

Cranial CT was performed the day after surgery, and the hematoma evacuation rate was assessed by author Gang Liu, who was blinded to the patients’ treatment and clinical outcome, based on the Slicer software, using the method described in our previous study.14

Statistical Analysis

The paired Wilcoxon test was used to compare the preoperative and postoperative GCS scores and hematoma volume. Statistical significance was set at p < 0.05. All analyses were completed using SPSS statistical software (version 19.0, IBM Corp.).

Results

There were 25 patients enrolled in the study, including 18 cases of putamen hemorrhage and 7 cases of lobar cerebral hemorrhage. Virtual reality was used in combination with augmented reality to ensure that the optimal trajectory was made and the transparent sheath reached the desired position. Satisfactory removal of the hematoma was achieved in all cases, although the removal was not always complete. In some cases, the decision was made to leave intraventricular hematoma that was hard to see or partial hematoma adjacent to an eloquent area. For patients taking aspirin, patients in whom complete hematoma removal was not achieved, and for patients in whom an intraventricular hematoma remained, a soft drainage tube was placed before wound closure, due to the risk of rebleeding or for residual hematoma drainage.

The median time from the first incision to suture completion was 50 minutes (range 40–70 minutes), and the actual endoscopic operating time was 30 minutes (range 15–50 minutes). Data processing and puncture trajectory design was completed within approximately 5 minutes.

The median blood loss was 80 ml (range 40–150 ml). No patient experienced postoperative rebleeding. The mean preoperative hematoma volume was 63.9 ± 26.6 ml, and the mean residual hematoma volume was 1.4 ± 1.8 ml, (p < 0.01), representing an average evacuation rate of 97%. The mean preoperative GCS score was 6.7 ± 3.2, and the mean GCS score 1 week after hematoma evacuation was 11.9 ± 3.1 (statistically significant improvement, p < 0.01).

A summary of the patients’ demographic and clinical characteristics is provided in Table 1.

Illustrative Cases

Case 21: A Putamen Hemorrhage

This 75-year-old man with a history of hypertension was admitted to our hospital after the sudden onset of unconsciousness and paralysis. Emergency cranial CT revealed a right putamen hemorrhage. The distance between
the center of the hematoma and the midline was measured and found to be approximately 2.7 cm (Fig. 1A). Using the hospital’s PACS, we achieved a digital 3D reconstruction of the patient’s head and right lateral projection of the hematoma (Fig. 1C). Using the Sina smartphone app, we overlapped the resulting combined image and the patient’s actual head using the ear, nose, and eye as landmarks. The hematoma’s projection on the right side of the patient’s head was localized and drawn on the scalp (Fig. 1D). Thus, we designed a transfrontal trajectory parallel to the sagittal plane 2.7 cm off midline. The entrance point was just behind the frontal hairline, and the target was the hematoma’s center; the depth was also measured (7.5 cm). A short, straight incision of approximately 4 cm (Fig. 2A) and a bone flap 2 cm in diameter (Fig. 2B) were designed. After the dura mater was opened, the local cortex was coagulated, an obturator was inserted into the target, the needle was withdrawn, and the syringe was used to relieve the high cranial pressure from the hematoma; then the sheath was introduced to the hematoma’s center. Endoscopic removal of the hematoma was performed with a suction device (Fig. 2C) until all of the hematoma in the visual field was evacuated (Fig. 2D). Cranial CT performed the next day revealed nearly total evacuation of the hematoma (Fig. 1B).

Case 3: A Temporoparietal Cerebral Hemorrhage

This 64-year-old man was admitted for sudden disturbance of consciousness. Cranial CT demonstrated a temporoparietal cerebral hemorrhage (Fig. 3A and B). Based on the hospital’s PACS and the Sina app, we achieved hematoma projection on the left lateral side of the patient’s head (Fig. 4A and B). The ideal bur-hole location point was determined by extending a line along the long axis of the hematoma far away from the visual pathway and language-related structures (Fig. 4C). Finally, a trajectory was designed from the superior occipital lobe parallel to the sagittal plane, and the depth and lateral-to-midline distance were measured (Fig. 4D). The rest of the procedure was similar to that described in Case 21. Cranial CT performed the next day revealed total evacuation of the hematoma (Fig. 3C and D).

Discussion

Whether patients benefit from the evacuation of spontaneous intracerebral hematomas remains unclear, but removing the hematoma can decrease intracranial pressure and reduce secondary injuries caused by mass effect. Currently, the primary surgical methods for hematoma evacuation are craniotomy and puncture drainage. How-

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HC to MD = hematoma center to midline distance; RV = residual volume.
ever, it appears that increasing numbers of hospitals are using minimally invasive endoscopic hematoma removal. Some studies have demonstrated that the method is associated with a reduced rate of iatrogenic injury.

Hematoma localization has been based on the surgeon’s experience in most reported studies of endoscopic hematoma evacuation, resulting in poor stability, unreliability, and difficulties with quality control. In some studies the hematoma has been localized based on neuronavigation, which can allow the desired position to be accurately reached, but the neuronavigation demands the thinnest layer of CT data. In addition, preparing for navigation is time-consuming, which is a drawback under emergency circumstances.

For endoscopic removal of the hematoma, introducing the sheath to the target precisely and accurately is the key to successful evacuation. In our study, with the help of the simple, fast, and economical procedure described in this article, neurosurgeons obtained satisfactory hematoma positioning and were able to introduce the sheath to the pre-established target; thus, the sheath swing angle was minimized and injury-related adverse effects were further reduced.

Depending on the site of the hematoma, we designed different puncture trajectories to achieve minimal injury to the normal brain: for most putamen hemorrhages, we used a transfrontal trajectory parallel to the sagittal plane. For thalamic hemorrhages, we used a superior occipital puncture trajectory. For lobar hemorrhages, based on the location, a shorter pathway was chosen, tailored to the individual case and taking care to avoid eloquent areas.

Methods of determining the working channel setup have varied in different studies; thus, surgical results have also varied. In our study, we used our own patented set of instruments. The set consists of a needle (which matches standard syringes), an obturator (diameter 1 cm), and a sheath (diameter 1.2 cm). According to the depth of the hematoma, sheaths of different lengths can be chosen. This set of instruments is shown in Fig. 5 (upper).

The sheath used in other reports was commonly a cylinder for the entire length, while our sheath had a leading edge that was slightly tapered and had an inclined plane tip. With this shape, the hematoma can easily move into the visual field of the working channel with the help of intracranial pressure.

After the obturator was inserted into the target, we withdrew the needle and used the syringe to evacuate some of the hematoma in order to relieve the high intracranial pressure and confirm placement of the obturator tip in the hematoma, and then the sheath was introduced into the hematoma’s center. The transparent sheath provides a working channel for endoscopic and surgical instruments, minimizing iatrogenic injury.

For hematoma evacuation, suction is first applied to the center of the hematoma. The brain tissue surrounding the hematoma and the higher pressure will automatically

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**FIG. 1.** Case 21. Putamen hematoma case and surgical design. Emergency cranial CT (A) revealed a right basal ganglia hemorrhage with a center-to-midline distance of 26.90 mm. An image of the hematoma in a right lateral view was projected onto a reconstruction of the patient’s head (C). Using the Sina neurosurgical assist Android smartphone app, we adjusted the reconstructed head until it matched the patient’s actual head in the sagittal view well. The hematoma’s projection onto the right side of the patient’s head was localized and drawn onto the scalp (D). A puncture trajectory 26.90 mm in length and parallel to the sagittal plane was designed. The entrance point was just behind the frontal hairline. The target was the center of the hematoma, at a measured depth of 7.5 cm. Postoperative CT revealed that the hematoma was totally evacuated (B). Figure is available in color online only.

**FIG. 2.** Case 21. Surgical process of putamen hematoma evacuation. A 4-cm straight incision parallel to the midline (26.9 mm) (A) with a 2-cm diameter bone flap (B) was designed. Endoscopic removal of the hematoma was performed with a suction device, with observation of the residual hematoma through the transparent sheath (C), until all of the hematoma in the visual field was evacuated (D). Figure is available in color online only.
push the hematoma to the bottom of the working channel, where it can be suctioned easily. Through the transparent side wall of the sheath, the surgeon can easily observe the direction and amount of residual hematoma, which can be removed by slightly swinging the sheath. The process of the evacuation should be from the deep to the shallow portion of the hematoma, and the sheath should be gradually pulled out until the hematoma is removed satisfactorily.

The surgeon should carefully evacuate the hematoma with the suction device to avoid causing damage to brain tissue around the hematoma. If arterial bleeding is observed, the suction device can be moved against the bleeding arterial vessel, and the assistant can use monopolar coagulation to stop the bleeding (see Fig. 5 lower). After satisfactory evacuation of the hematoma, its wall is overlaid by hemostatic gauze. Finally, if no bleeding is observed, the wound is closed.

The time required for craniotomy in this study was approximately 5–10 minutes, the hematoma evacuation time was 15–50 minutes, and the wound closing time was about 10 minutes, so the total operation time was within 70 minutes. As the surgical wound was small, there was less iatrogenic injury, and the amount of intraoperative blood loss was less than 150 ml in all cases. An endoscopically guided sheath swing facilitates the wide observation of the surgical field and reduces the dead area of the view field. In this study, satisfactory hematoma evacuation was achieved in all cases, although in some instances intraventricular hematomas or hematoma adjacent to eloquent areas were not fully removed.

We did not apply commercial neuronavigation (for thinner layer scanning) for hematoma location in this study, and this significantly reduced the time spent in the preparation process. Preoperative surgical planning was easily accomplished. Nearly all hospitals have PACS, smartphones are commonly used worldwide, and the Sina neurosurgical assist is a free Android app with an English version that is downloadable from the Google Play Store. Thus our method reduced barriers to care and saved medical costs.

Although endoscopic surgery for spontaneous supratentorial intracerebral hematoma seems encouraging, the number of patients enrolled in the study was small and there was no control group. A prospective randomized controlled study is needed to provide an evidence-based result.

**Conclusions**

The virtual reality and augmented reality techniques used in this study facilitated accurate and precise hematoma positioning, optimal puncture trajectory design, and introduction of a transparent sheath to the center of the hematoma for establishment of a working channel. The use of a transparent sheath for the suction apparatus and endoscope is helpful in identifying hematoma orientation and scope. Its use in combination with virtual reality and augmented reality guidance facilitated hematoma evacuation.
via a minimally invasive approach and resulting in good outcomes and relatively short duration of surgery.

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References


Disclosures

The authors report no conflict of interest concerning the materials or methods used in this study or the findings specified in this paper.

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