Evaluation of mobility and stability in the Discover artificial disc: an in vivo motion study using high-accuracy 3D CT data

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OBJECT Artificial disc replacement (ADR) devices are unlike implants used in cervical fusion in that they are continuously exposed to stress not only within the implant site but also at their site of attachment to the adjacent vertebra. An imaging technique with higher accuracy than plain radiography and with the possibility of 3D visualization would provide more detailed information about the motion quality and stability of the implant in relation to the vertebrae. Such high-accuracy studies have previously been conducted with radiostereometric analysis (RSA), which requires implantation of tantalum markers in the adjacent vertebrae. The aim of this study was to evaluate in vivo motion and stability of implanted artificial discs. A noninvasive analysis was performed with CT, with an accuracy higher than that of plain radiographs and almost as high as RSA in cervical spine.

METHODS Twenty-eight patients with ADR were included from a larger cohort of a randomized controlled trial comparing treatment of cervical radiculopathy with ADR or anterior cervical decompression and fusion. Surgical levels included C4–7; 18 patients had 1-level surgery and 10 patients had 2-level surgery. Follow-up time ranged from 19 to 50 months, with an average of 40 months. Two CT volumes of the cervical spine, 1 in flexion and 1 in extension, were obtained in each patient and then spatially registered using a customized imaging tool, previously used and validated for the cervical spine. Motion between the components in the artificial disc, as well as motion between the components and adjacent vertebrae, were calculated in 3 planes. Intraclass correlation (ICC) between independent observers and repeatability of the method were also calculated.

RESULTS Intrinsic motion, expressed as degrees in rotation and millimeters in translation, was detectable in a majority of the ADRs. In the sagittal plane, in which the flexion/extension was performed, sagittal rotation ranged between 0.2° and 15.8° and translation between 0.0 and 5.5 mm. Eight percent of the ADRs were classified as unstable, as motion between at least 1 of the components and the adjacent vertebra was detected. Five percent were classified as ankylosic, with no detectable motion, and another 8% showed very limited motion due to heterotopic ossification. Repeatability for the motion in the sagittal plane was calculated to be 1.30° for rotation and 1.29 mm for translation (95% confidence level), ICC 0.99 and 0.84, respectively. All 3 patients with unstable devices had undergone 1-level ADRs at C5–6. They all underwent revision surgery due to increased neck pain, and instability was established during the surgery.

CONCLUSIONS The majority of the artificial discs in this study showed intrinsic mobility several years after implantation and were also shown to be properly attached. Implant instability was detected in 8% of patients and, as all of these patients underwent revision surgery due to increasing neck pain, this might be a more serious problem than heterotopic bone formation.

Clinical trial registration no.: ISRCTN44347115 (www.ISRCTN.com)


KEY WORDS artificial disc replacement; mobility; computed tomography; instability; revision surgery
WITH the introduction and increased use of artificial disc replacement (ADR) during the last 2 decades there is also a need to evaluate and understand how these implants behave in vivo, in terms of both motion and stability. Focus in previous studies has been on motion within the discs and heterotopic ossification (HO) surrounding the discs, while there is very limited knowledge about stability of the implants and how different techniques for anchoring the devices affect this. The aim of this study was to evaluate range of motion (ROM) and stability in the Discover artificial disc (DePuy Spine) segments using a 3D CT method previously validated for cervical spine by Svedmark and colleagues. The method has the capability to measure motion both within the implant and relative to the adjacent bone with an accuracy that has been previously established. Previous studies on spinal mobility have been performed with varying accuracy, depending on the technique used. Radiostereometric analysis (RSA) has been shown to be the most accurate; however, the technique always requires implantation of tantalum markers and is therefore an invasive method. The accuracy is also dependent on how the markers are distributed within the vertebrae. The technique that we have used is noninvasive and therefore easier to use than RSA in clinical practice. In this study, we also took the opportunity to test repeatability between 2 different observers.

**Methods**

The patients in this study were all recruited from a larger multicenter randomized controlled trial (RCT) comparing reconstruction with anterior cervical decompression and fusion and ADR. The RCT was registered with the ISRCTN registry (www.ISRCTN.com), and its registration number is ISRCTN44347115. The primary outcome variable in the RCT was the neck disability index (NDI), with scores collected preoperatively and 2 years after surgery. Twenty-eight patients were included. Informed consent was obtained from all patients, and the study was approved by the regional ethics committee in Stockholm. These 28 patients accounted for 35% of all those patients in the RCT who were treated with ADR, and they were selected on the basis of living in the Stockholm area, with easy access to the examining clinic. Sixteen (57%) were women, and the average age was 46.6 years (range 37–57 years). All investigations were performed at the same clinic (Aleris, Löwenströmska Hospital, Sweden), with a standard procedure described in detail below. Surgery was performed by 4 surgeons, using a standard anterior approach, with decompression of affected nerve tissue, including resection of the posterior longitudinal ligament. All of the patients were given 25 mg of diclofenac 3 times a day orally for 10 days after surgery, with the intention of minimizing the formation of heterotopic bone around the prostheses. The distribution of surgical levels at the time of CT scan is shown in Table 1. The mean time between surgery and CT scanning was 40 months (range 19–50 months). The Discover artificial disc was used in all patients randomized to ADR. The Discover disc does not have an FDA approval and is not available for commercial use in the United States. The device is an unconstrained ball and socket construction consisting of 3 parts—2 titanium endplates with a half sphere of polyethylene fixed in the caudal section. Six small spikes impacted into the vertebral endplates provide primary stability. The contact surface is also coated with hydroxyapatite (HA) to promote ingrowth of bone and fixation. Two CT scans of each patient were obtained with the patients placed in the CT scanner on their left side at a 90° angle to the supine position, and their head supported by a stiff pillow. With this support for the head, it was possible to adjust the position so that the cervical spine was in a neutral position before scanning. This position was chosen after a number of trials in the supine position, in which flexion and extension required more force due to restriction of the head and neck support. Lying on their side, patients could easily move their head into maximal flexion and maximal extension. A CT scan was obtained in each position, creating a “flexion CT volume” and an “extension CT volume.” The CT scans were obtained with a Somatom Definition AS clinical scanner (Siemens) using a standard clinical low-dose protocol. The radiation dose was calculated to be 0.33 mSv per scan. Slices were reconstructed at 0.6-mm increments, which was different from the study by Svedmark, where slices were reconstructed at 1 mm. All image analysis was performed using a 3D volume fusion (spatial registration) tool, which has been previously described. Having validated accuracy (Table 2), this semiautomated tool provides landmark-based fusion of 2 volumes, registering the flexion CT volume with the extension CT volume via a variety of 3D transform modules, from simple rigid body, to 3D warping, to user defined. The computer’s 2D pointing device was used to specify landmarks on isosurfaces, with the software automatically finding the corresponding 3D points. A technical description can be found in previous publications.

The kinematics analysis measured 2 motions: 1) movement of the prosthetic lower component relative to the upper component and 2) movement between any of the components of the ADR and the attaching vertebrae. The procedure for each requires manually selecting a small number of landmarks (Fig. 1) on isosurfaces, followed by the automatic calculation of the desired movement by the image analysis tool. For more detailed information on this method, please see the previous studies by Svedmark and colleagues.  If no motion between the lower and upper prosthetic component could be detected, the segment was classified as ankylotic. If there was any detectable motion between any of the prosthetic components and the vertebra to which they were attached, it was classified as an

| TABLE 1. Distribution of surgical levels and mean rotation in the sagittal plane* |
|-----------------|-----------------|-----------------|-----------------|-----------------|
| Level           | 1-Level ADR     | 2-Level ADR     | Mean Sagittal   | Range (SD)      |
|                 | 1              | 2              | Rotation       |                 |
| C4–5            | 2              | 0              | 6.7            | 6.5–7.0 (0.4)   |
| C5–6            | 10             | 10             | 6.2            | 1.0–15.8 (4.1)  |
| C6–7            | 6              | 10             | 3.0            | 0.2–6.0 (2.4)   |

* All values are degrees.
unstable or loose device. To evaluate the interobserver repeatability, 2 observers independently analyzed all patient volumes. A total of 38 prostheses were analyzed, as 10 patients had 2-level ADRs.

Statistics

ROM within each implant is presented as mean values with standard deviations (SDs); rotation is measured in degrees and translation in millimeters. The Fisher exact test was used to compare motion between the different levels. A Student t-test for independent samples was used to compare motion between the caudal and the apical prostheses in the group of patients with 2-level ADR. A 95% CI was calculated with the Wilson quadratic method for the possibility of loosening or ankylosis of the prosthesis.6 Intraclass correlation (ICC) was calculated between the 2 observers for all 28 patients, 38 prostheses in total. ICC was considered good if Cohen’s kappa coefficient was > 0.61 and very good if it was > 0.80.8 The standard error of measurement was calculated and is generally highly associated with the reliability coefficient, kappa, and may be more informative about the range within which the true value is most likely to fall. Repeatability was calculated with a 95% confidence level for all motions and was defined as the maximum deviation between measurements under the same conditions and with the same measuring instrument. Pre- and postoperative NDI values are presented as means with SDs and compared by use of the Wilcoxon signed-rank test. Statistical significance was set at a p value < 0.05. Statistica software version 11 (StatSoft Inc.) was used for all calculations.

Results

All prostheses could be successfully evaluated both numerically and visually (Fig. 2). In the sagittal plane, in which the principal movement (flexion-extension) was performed, the mean rotation was 5.1° (SD 3.8°) with a range of 0.2° to 15.8°, and the mean translation was 1.0 mm (SD 1.2 mm) with a range of 0.0–5.5 mm. The rotation and translation in the other planes were, as expected, small, and motions in all 3 planes are presented in Table 3. There was a statistically significant difference in mean sagittal rotation, with less motion at the C6–7 level (mean 3.0°) than at the C5–6 level (mean 6.2°) (p < 0.01, Table 1). No significant difference could be seen between the C4–5 level and the other levels. The mean rotation in the single-level ADR group was 5.7° (SD 4.1°). In the 2-level ADR group, the mean rotations in the caudal and the apical ADRs were 3.3° (SD 2.7°) and 5.7° (SD 3.9°), respectively. The difference was not statistically significant (p = 0.08). When motion was compared between 1- and 2-level surgeries altogether, no statistically significant difference was found (p = 0.52). The mean NDI score in this cohort changed from 64 (SD 16.7) preoperatively to 40 (SD 20.7) at 2-year follow-up (p = 0.01).

Evaluation of the registered volumes showed that in 2 prostheses (5%) there was a clear ankylosis with bridging bone around the ADR and no detectable motion. Three other prostheses (8%) had bone masses that bridged the operated segment but had detectable motion and were therefore not classified as ankylositic. One of these prostheses was the lower level of a 2-level replacement with a fused upper level, and 2 of them were 1-level disc replacements. The probability for ankylosis was calculated to be between 1% and 17% (95% CI). In 3 (8%) of the devices there was a detectable motion between a component of the ADR and the bone. There was also osteolysis in conjunction with the loose prosthetic component in 2 of these (Fig. 3). The probability for loosening was calculated to be between 3% and 21% (95% CI). All loose components were detected in the 1-level group and at the C5–6 level. In all of these cases, it was the upper component of the prosthesis that showed motion in relation to the vertebra. Additionally, there was osteolysis in conjunction with 1 more apical component, without detectable motion between the bone and component (Fig. 4). The relative measured movement between the loose components and

<table>
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<tr>
<th>Plane</th>
<th>Rotation (°)</th>
<th>Translation (mm)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Sagittal</td>
<td>0.7</td>
<td>0.4</td>
</tr>
<tr>
<td>Coronal</td>
<td>0.4</td>
<td>0.2</td>
</tr>
<tr>
<td>Transaxial</td>
<td>0.2</td>
<td>0.5</td>
</tr>
</tbody>
</table>

### Table 2. Accuracy of 3D CT in all 3 planes

![Interactive 3D isosurface representation of the prosthesis. Numbered landmarks are situated on elevated pegs on the upper component. Automatically generated Landmark 7 is shown below Landmark 2 (third landmark from the right on the upper component).](image1)

![Visual presentation of 3D motion. The lower component is a “fusion” of the 2 CT volumes, and the upper image depicts motion in flexion (green) and in extension (yellow).](image2)
the vertebrae is presented in Table 4. No association between ankylosis or loosening and time to follow-up could be seen. The repeatability between 2 observers in the sagittal plane was 1.3° and 1.3 mm (95% confidence level), and the ICC was good or very good except for translation in the coronal plane, which was classified as “fair.” The ICC in the test-retest showed kappa coefficients varying between 0.30 and 0.99 (Table 5). All patients in whom instability was detected underwent later revision, where the radiological finding could be established intraoperatively, as the apical parts were not properly fixed to the adjacent vertebrae. All the lower components of the prostheses were fixed, however, and substantial force was required to remove them. As there were clear signs of bone loss in the anterior part of the upper vertebrae, the segments had to be reconstructed with cages, and in 1 patient this resulted in a corpectomy and a 2-level fusion to restore alignment. In 1 of the removed discs, there was also obvious wear of the polyethylene sphere.

Discussion

When studying spinal kinematics, there are several different motions that can be observed, and the biomechanics are complex. In this study, we have chosen to evaluate motion between the components of implanted prostheses and motion of the prostheses relative to the bone in voluntary extension and flexion. However, motion was measured in 3 planes, and this shows, not surprisingly, that there are detectable and coupled motions in different planes. This can be partly explained by the impossibility of achieving motion in just 1 plane in a clinical setting, and partly by the finding that motion segments do not always move symmetrically. It should also be pointed out that measurements with this technique are done only in the end positions of flexion and extension. For evaluation of the whole motion, dynamic methods are required. The accuracy of the technique used in this study has previously been evaluated and was determined to be not as good as RSA in vitro; however, it is almost as good as RSA in vivo for the cervical spine. As slice thickness in this study was thinner than in the validation study, we can assume that the accuracy might be even higher. In this study, we also added reliability tests between observers. The ICCs between observers were good for most motions but only “fair” for coronal translation. This can be explained by the fact that the ROM in most patients does not exceed the accuracy of the measurement in that plane. The ICC is very good for the motion that patients performed between the 2 scans, sagittal rotation. This is also the motion with the widest range; the error of the method is relatively smaller in these measurements. The aims of ADR are for the implants to

### Table 3. Measured motion in all 3 planes for all prosthetic levels

<table>
<thead>
<tr>
<th>Motion</th>
<th>Mean (SD)</th>
<th>Range</th>
</tr>
</thead>
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<tr>
<td><strong>Rotation in degrees</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Coronal</td>
<td>1.4 (1.5)</td>
<td>0.0–5.5</td>
</tr>
<tr>
<td>Sagittal</td>
<td>5.1 (3.8)</td>
<td>0.2–15.8</td>
</tr>
<tr>
<td>Transaxial</td>
<td>1.4 (1.5)</td>
<td>0.0–6.2</td>
</tr>
<tr>
<td><strong>Translation in mm</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Coronal</td>
<td>0.2 (0.2)</td>
<td>0.0–0.8</td>
</tr>
<tr>
<td>Sagittal</td>
<td>1.0 (1.2)</td>
<td>0.0–5.5</td>
</tr>
<tr>
<td>Transaxial</td>
<td>0.9 (0.8)</td>
<td>0.0–2.7</td>
</tr>
</tbody>
</table>

FIG. 3. CT images from Case 3, one of the 3 cases in which osteolysis was seen in conjunction with a loose ADR component. Motion is evident between the upper component of the prostheses and bone in both flexion (left) and extension (right). Osteolysis can be seen in the anterior part of the upper vertebrae, adjacent to the component.

FIG. 4. CT image obtained in the patient who had osteolysis in conjunction with the more apical component without detectable motion between the bone and the component. Osteolysis can be seen around the pegs of the upper component; no movement between component and bone was observed.

### Table 4. The relative measured movement between the loose component and the vertebra

<table>
<thead>
<tr>
<th>Case No.</th>
<th>Rotation (°)</th>
<th>Translation (mm)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Coronal</td>
<td>Sagittal</td>
</tr>
<tr>
<td>1</td>
<td>1.1</td>
<td>0.8</td>
</tr>
<tr>
<td>2</td>
<td>0.9</td>
<td>1.6</td>
</tr>
<tr>
<td>3</td>
<td>0.7</td>
<td>3.4</td>
</tr>
</tbody>
</table>
maintain cervical mobility and for the components of the ADR to achieve sufficient stability relative to the adjacent vertebrae. ROM in this study was significantly less at C6–7 than at C5–6. The ROM at C4–5 was almost the same as for C5–6, but a statistically significant difference could not be established in comparison with C6–7, probably because of the small sample size in the C4–5 group. There may be several conceivable factors influencing these variations, but, most likely, they are explained by differences in preoperative segment mobility due to varying degrees of disc degeneration. As no preoperative CT scans were available, no study of the correlation between preand postoperative ROM was performed. A higher degree of degeneration in the segment could, theoretically, lead to the need for a greater extent of bone removal from end plates and uncovertebral joints to achieve sufficient decompression. Such interaction might enhance the development of HO with inhibited ROM in that segment. On the other hand, a larger ROM, as seen in the C4–5 and C5–6 segments, might instead cause higher stress on the surface of fixation between the implant and the vertebra, leading to instability and migration of the ADR. All of the unstable discs were found at the C5–6 level, which could strengthen this theory. Migration in a worst-case scenario could cause serious and irreversible neurological damage. None of the patients in this study had any neurological impairment, and the decision to undergo revision surgery was due to the results of this motion analysis, showing highly unstable implants, in combination with increased neck pain. A previously published motion study of the same artificial disc reported migration in 6 of 55 patients (11%), although evaluations were done with plain radiographs. Other previous radiographic studies on other artificial discs have not reported similar figures concerning loosening or migration to the same extent. This can be explained by postulating that no such problems actually existed, or that the imaging technique was not of sufficient accuracy or resolution to detect it. Furthermore, if motion is measured only in parts of the prosthesis and not relative to the bone, vital information about implant stability is lost. We compared plain radiographs, obtained prior to secondary surgery, to the 3D CT analysis concerning instability of all the patients who underwent reoperation. Motion within the implants could be detected, but instability relative to the vertebra could not be established in flexion and extension on plain radiographs. The definition of an unstable or loose prosthesis is also somewhat unclear since there might always be some micromotion between implants and bone. We defined instability or loosening as a detectable motion between bone and prosthesis when comparing the 2 scans. It can be argued that the measured motion between implants and adjacent vertebrae showed measured values close to the limit of the accuracy of the method. However, the combination of these findings and increasing neck pain in these 3 patients led to the decision for revision surgery, where the radiological findings were confirmed. In another patient, we found radiographic osteolysis around the spikes of the apical part of the prosthesis, without any detectable motion relative to adjacent bone (Fig. 4). This is an interesting finding for which there may be various theories. First, there is a possibility that the prosthesis was unstable but that the motion was so small that it was not detectable with this method. Second, the provocation was inadequate so that the prosthetic part did not move in that specific rotation. In that case, this is a finding of a possible asymptomatic, early loosening. However, primary osteolysis is also possible and raises the question of what comes first, osteolysis or loosening? One can speculate that primary osteolysis might be caused by wear associated with microparticles, but support for this cannot be shown in this study. The calculated 95% CI for loosening shows a wide range in this study and should be interpreted with caution since the sample size is relatively small. The problem with formation of heterotopic bone may cause reduced mobility and even ankylosis. The influence of NSAIDs on bone formation and ingrowth into HA coating is controversial and may, if there is an effect, be dependent on dosage. The patients in this study were all given low doses of diclofenac for 10 days, which may have decreased HO but also ingrowth of bone to the HA-coated titanium end-plates. We cannot determine whether the NSAIDs in this study had any effect on HO, and these data have to be compared with data from other studies. The frequencies of HO in other studies vary, and there does not seem to be a clear correlation to patient outcome. Suchomel et al. found significant HO in 45% and ankylosis in 18% in a cohort of 50 patients in a 4-year follow-up after treatment with the ProDisc-C. Tu et al. have performed studies on HO with CT on patients treated with the Bryan artificial disc. They did not find the same high incidence of HO and concluded that appropriate carpentry is an important factor to avoid development of HO. Wu et al. found a significantly higher incidence of HO in 2-level surgeries than in 1-level surgeries, 75% and 40%, respectively. In a meta-analysis published by Chen et al., no clear association between the formation of HO and clinical outcome was found. The McAfee scale with 5 gradations of HO has been used in many studies and has been validated with regard to intraobserver reliability. We did not further analyze or grade the presence of heterotopic bone, but the motion analysis revealed that 2 prostheses were totally ankylosed and 3 were inhibited in motion due to heterotopic bone formation. Theoretically, an ADR that loses motion due to HO will function in the same way as a fusion. However, knowledge about loose, and in the longer term possibly migrat-

### Table 5. Results of the validation between 2 observers

<table>
<thead>
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<th>Motion</th>
<th>ICC</th>
<th>Repeatability</th>
<th>SEM</th>
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<tr>
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<td>0.95</td>
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<tr>
<td>Sagittal</td>
<td>0.99</td>
<td>1.30</td>
<td>0.47</td>
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<td>Transaxial</td>
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<td>0.93</td>
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</tr>
<tr>
<td>Coronal</td>
<td>0.30</td>
<td>0.77 mm</td>
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</tr>
<tr>
<td>Sagittal</td>
<td>0.84</td>
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<td>0.46</td>
</tr>
<tr>
<td>Transaxial</td>
<td>0.66</td>
<td>1.78 mm</td>
<td>0.64</td>
</tr>
</tbody>
</table>

SEM = standard error of measurement.
ing ADR devices, is very limited. Cunningham et al. studied osseointegration of 29 implants in both the cervical and the lumbar spine in relation to placement. They found less ingrowth of bone in poorly placed implants, although the difference was not statistically significant. In another study of interest relating to this issue, Palissonny et al. investigated the stress patterns in the vertebral body in correlation to implant size. They found, not surprisingly, that a smaller implant footprint resulted in a higher load and stress to the endplates in lumbar spine, but it can be assumed that the same conditions prevail in the cervical spine. In our study, only 1 type of device was evaluated, but it would be desirable to compare stability between different designs and concepts, as the method of fixation might influence stability. A weakness of this study is that preoperative data were not available. Such data would have been desirable, especially when interpreting differences in postoperative motion between different cervical levels; these data can possibly be provided in future studies. Another weakness is the long range in time between surgery and CT scanning, as both prevalence of HO and implant instability, theoretically, might increase with time. The small sample size is also a limitation, and associations between radiographic pathology and clinical outcome cannot be made. Funding from the manufacturer of the implant was received for this study but the support was totally unrestricted, and the company had no influence in the design of the study or in analysis of the data.

Conclusions

The majority of the Discover artificial discs in this study maintained cervical mobility after implantation, and the discs remained stable, with proper attachment. However, 8% of the Discover discs in this study exhibited clear signs of instability, which was confirmed later by revision surgery. Thirteen percent of the treated levels were ankylosic or showed clearly inhibited motion due to HO. All of the patients with confirmed instability underwent revision surgery because of increased neck pain, while none of the patients with ankylosis or inhibited motion needed revision surgery. This study indicates also that the development of instability and nonfixation poses a greater risk of revision surgery than does the development of inhibited motion due to ankylosis or HO.

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References

Mobility and stability in the Discover artificial disc


Author Contributions

Conception and design: Skeppholm, Olerud. Acquisition of data: Skeppholm, Svedmark, Noz, Maguire. Analysis and interpretation of data: Skeppholm, Svedmark, Noz, Maguire, Olivecrona. Drafting the article: Skeppholm. Critically revising the article: Svedmark, Noz, Maguire, Olivecrona, Olerud. Reviewed submitted version of manuscript: Svedmark, Noz, Maguire, Olivecrona, Olerud. Approved the final version of the manuscript on behalf of all authors: Skeppholm. Statistical analysis: Skeppholm. Administrative/technical/material support: Olivecrona. Study supervision: Olivecrona, Olerud.

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